

1. $\mathcal{E} = (\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n)$: ORDERED COLLECTION IN A VECTOR SPACE V

(a) $[\mathcal{E}] : \mathbb{R}^n \rightarrow V$ IS THE LINEAR COMBINATION FUNCTION, DEFINED AS FOLLOWS: (DOMAIN \mathbb{R}^n , CODOMAIN V)

$$[\mathcal{E}] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = x_1 \vec{v}_1 + x_2 \vec{v}_2 + \dots + x_n \vec{v}_n$$

↑ COLLECTION
↑ COEFFICIENT VECTOR
↓ CORRESPONDING L.C. OF \mathcal{E}

(b) $[\mathcal{E}]$ IS A LINEAR TRANSFORMATION FROM \mathbb{R}^n TO V :

⊙ (SHOW $[\mathcal{E}]\vec{0} = \vec{0}$)

$$[\mathcal{E}] \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} = 0\vec{v}_1 + 0\vec{v}_2 + \dots + 0\vec{v}_n = \vec{0} + \dots + \vec{0} = \vec{0} \quad \checkmark$$

⊙ (SHOW THAT $\forall \vec{x} \in \mathbb{R}^n$ AND $q \in \mathbb{R}$, $[\mathcal{E}](q\vec{x}) = q[\mathcal{E}]\vec{x}$)

LET $\vec{x} \in \mathbb{R}^n$ AND $q \in \mathbb{R}$ BE GIVEN; THEN $\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$, WHERE $x_1, \dots, x_n \in \mathbb{R}$.

$$\begin{aligned} \text{NOW, } [\mathcal{E}](q\vec{x}) &= [\mathcal{E}]\left(q \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}\right) = [\mathcal{E}] \begin{bmatrix} qx_1 \\ \vdots \\ qx_n \end{bmatrix} \\ &= (qx_1)\vec{v}_1 + (qx_2)\vec{v}_2 + \dots + (qx_n)\vec{v}_n \\ &= q(x_1\vec{v}_1 + x_2\vec{v}_2 + \dots + x_n\vec{v}_n) \\ &= q[\mathcal{E}] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = q[\mathcal{E}]\vec{x} \quad \checkmark \end{aligned}$$

⊙ (SHOW THAT $\forall \vec{x}, \vec{y} \in \mathbb{R}^n$, $[\mathcal{E}](\vec{x} + \vec{y}) = [\mathcal{E}]\vec{x} + [\mathcal{E}]\vec{y}$)

LET $\vec{x}, \vec{y} \in \mathbb{R}^n$ BE GIVEN; THEN $\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$ AND $\vec{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$, WHERE $x_i, y_i \in \mathbb{R}$.

$$\begin{aligned} \text{NOW, } [\mathcal{E}](\vec{x} + \vec{y}) &= [\mathcal{E}]\left(\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} + \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}\right) = [\mathcal{E}] \begin{bmatrix} x_1 + y_1 \\ \vdots \\ x_n + y_n \end{bmatrix} \\ &= (x_1 + y_1)\vec{v}_1 + (x_2 + y_2)\vec{v}_2 + \dots + (x_n + y_n)\vec{v}_n \\ &= (x_1\vec{v}_1 + x_2\vec{v}_2 + \dots + x_n\vec{v}_n) + (y_1\vec{v}_1 + y_2\vec{v}_2 + \dots + y_n\vec{v}_n) \\ &= [\mathcal{E}] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} + [\mathcal{E}] \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = [\mathcal{E}]\vec{x} + [\mathcal{E}]\vec{y} \quad \checkmark \end{aligned}$$

BY ⊙, ⊙, AND ⊙, $[\mathcal{E}] : \mathbb{R}^n \rightarrow V$ IS A LINEAR TRANSFORMATION ■

2. $\mathcal{E} = (\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n)$: ORDERED COLLECTION IN A VECTOR SPACE V

(a) $\text{IM}[\mathcal{E}]$ IS JUST THE SPAN OF \mathcal{E} !

$$\begin{aligned} \text{WHY? } \text{IM}[\mathcal{E}] &\stackrel{\text{DEF}}{=} \{[\mathcal{E}]\vec{x} : \vec{x} \in \mathbb{R}^n\} \\ &= \left\{ [\mathcal{E}] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} : x_1, \dots, x_n \in \mathbb{R} \right\} \\ &= \left\{ x_1\vec{v}_1 + x_2\vec{v}_2 + \dots + x_n\vec{v}_n : x_1, \dots, x_n \in \mathbb{R} \right\} \\ &\stackrel{\text{DEF}}{=} \text{SPAN } \mathcal{E} \quad (\text{THE SET OF ALL L.C.'S OF } \mathcal{E}!) \end{aligned}$$

(b) $\text{KER}[\mathcal{E}]$ GIVES US THE COEFFICIENT VECTORS FOR ALL POSSIBLE LINEAR RELATIONS ON \mathcal{E} .

$$\begin{aligned} \text{WHY? } \text{KER}[\mathcal{E}] &\stackrel{\text{DEF}}{=} \left\{ \vec{x} \in \mathbb{R}^n : [\mathcal{E}]\vec{x} = \vec{0} \right\} \\ &= \left\{ \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} : x_1, \dots, x_n \in \mathbb{R} \text{ AND } [\mathcal{E}] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \vec{0} \right\} \\ &= \left\{ \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} : x_1, \dots, x_n \in \mathbb{R} \text{ AND } x_1\vec{v}_1 + x_2\vec{v}_2 + \dots + x_n\vec{v}_n = \vec{0} \right\} \\ &\quad \uparrow \qquad \qquad \qquad \uparrow \\ &\text{THE SET OF ALL COEFFICIENT VECTORS THAT GIVE LINEAR RELATIONS ON } \mathcal{E}. \end{aligned}$$

3. $\mathcal{E} = (\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n)$: ORDERED COLLECTION IN A VECTOR SPACE V

(a) IF \mathcal{E} IS L.I. IN V , THEN $[\mathcal{E}]$ IS INJECTIVE,
BECAUSE $\text{KER}[\mathcal{E}]$ WILL BE $\{\vec{0}\}$.

WHY? AS NOTED IN 2(b), THE VECTORS OF $\text{KER}[\mathcal{E}]$ CORRESPOND TO THE LINEAR RELATIONS ON \mathcal{E} ; IF \mathcal{E} IS L.I., THEN THE ONLY L.R. ON \mathcal{E} IS THE TRIVIAL ONE, SO $\text{KER}[\mathcal{E}] = \{\vec{0}\}$, WHICH FROM THE PREVIOUS PROBLEM SET WE KNOW MEANS THAT $[\mathcal{E}]$ IS INJECTIVE.

ALTERNATIVE EXPLANATION (NOT AS GOOD OF PRACTICE WITH USING OUR NEW TERMINOLOGY): IF \mathcal{E} IS L.I. IN V , THEN EACH VECTOR OF V CAN BE WRITTEN AS A L.C. OF \mathcal{E} IN AT MOST ONE WAY, SO $[\mathcal{E}]$ CAN HIT EACH $\vec{v} \in V$ AT MOST ONCE — I.E., $[\mathcal{E}]$ IS INJECTIVE.

(b) IF \mathcal{E} SPANS V , THEN $[\mathcal{E}]$ IS SURJECTIVE,
BECAUSE $\text{IM}[\mathcal{E}]$ WILL BE ALL OF V .

WHY? AS NOTED IN 2(a), $\text{IM}[\mathcal{E}] = \text{SPAN } \mathcal{E}$; IF \mathcal{E} SPANS V , THEN $\text{IM}[\mathcal{E}] = \text{SPAN } \mathcal{E} = V$, SO BY DEFINITION, $[\mathcal{E}]$ IS SURJECTIVE.

ALTERNATIVE EXPLANATION: IF \mathcal{E} SPANS V , THEN EACH VECTOR OF V CAN BE WRITTEN AS A L.C. OF \mathcal{E} IN AT LEAST ONE WAY, SO $[\mathcal{E}]$ HITS EACH $\vec{v} \in V$ AT LEAST ONCE — I.E., $[\mathcal{E}]$ IS SURJECTIVE.

(c) IF \mathcal{E} IS A BASIS FOR V , THEN $[\mathcal{E}]$ IS BIJECTIVE.

WHY? IF \mathcal{E} IS A BASIS FOR V , THEN \mathcal{E} IS L.I. IN V AND SPANS V , SO BY (a) AND (b), $[\mathcal{E}]$ IS BOTH INJECTIVE AND SURJECTIVE — I.E., $[\mathcal{E}]$ IS BIJECTIVE.

ALTERNATIVE EXPLANATION: IF \mathcal{E} IS A BASIS FOR V , THEN EACH VECTOR OF V CAN BE WRITTEN AS A L.C. OF \mathcal{E} IN EXACTLY ONE WAY, SO $[\mathcal{E}]$ PAIRS UP EACH $\vec{x} \in \mathbb{R}^m$ WITH ONE $\vec{v} \in V$ AND VICE-VERSA — I.E., $[\mathcal{E}]$ IS BIJECTIVE.

* A BIJECTIVE LINEAR TRANSFORMATION IS, BY DEFINITION, AN ISOMORPHISM.

4. $\mathcal{E} = (\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n)$: ORDERED COLLECTION IN \mathbb{R}^m ; $[\mathcal{E}] \rightsquigarrow$ MATRIX A

E.G., $\mathcal{E} = \left(\begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 1 \\ 5 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix} \right)$ IN \mathbb{R}^3 : $[\mathcal{E}] \rightsquigarrow \begin{bmatrix} 1 & 4 & 0 & -1 \\ 0 & 1 & 2 & 1 \\ 2 & 5 & 0 & -1 \end{bmatrix} = A$

(a) A HAS m ROWS AND n COLUMNS;
ROWS: SIZE OF COLUMN VECTORS COLS: # OF COLUMN VECTORS

E.G. AS ABOVE: A IS A 3×4 MATRIX.

THUS, IT IS AN m BY n MATRIX.

DIMENSIONS OF THE MATRIX:
ROWS \times COLUMNS

(b) IF $\vec{x} \in \mathbb{R}^n$, $A\vec{x} \stackrel{\text{DEF}}{=} [\mathcal{E}]\vec{x}$ IS A LINEAR COMBINATION OF \mathcal{E} ,
I.E., A LINEAR COMBINATION OF THE COLUMNS OF A
(WITH COEFFICIENTS GIVEN BY THE ENTRIES OF \vec{x}).

E.G. AS ABOVE: $\begin{bmatrix} 1 & 4 & 0 & -1 \\ 0 & 1 & 2 & 1 \\ 2 & 5 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 2 \\ -1 \end{bmatrix} = 1 \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} + 0 \begin{bmatrix} 4 \\ 1 \\ 5 \end{bmatrix} + 2 \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix} - 1 \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 3 \end{bmatrix}$

(c) JUST AS WITH $[\mathcal{E}]$, $A: \mathbb{R}^n \rightarrow \mathbb{R}^m$
DOMAIN \mathbb{R}^n CODOMAIN \mathbb{R}^m
COEFFICIENTS IN \mathbb{R}^n \mapsto L.C. IN \mathbb{R}^m

E.G. AS ABOVE, $A: \mathbb{R}^4 \rightarrow \mathbb{R}^3$.

[A: m x n MATRIX ARISING FROM $\mathcal{B} = (\vec{v}_1, \dots, \vec{v}_n)$ IN \mathbb{R}^m]

5. $N(A) = \{ \vec{x} \in \mathbb{R}^n : A\vec{x} = \vec{0} \}$ (I.E., THE KERNEl OF THE L.T. A)

- $N(A)$ IS A SUBSPACE OF \mathbb{R}^n (THE DOMAIN OF THE L.T. A)
- WE CAN FIND A BASIS FOR $N(A)$ SIMPLY BY SOLVING THE HOMOGENEOUS SYSTEM $A\vec{x} = \vec{0}$ AND SPLITTING OUR SOLUTION AS THE SPAN OF ITS FREE VARIABLES' CONTRIBUTIONS.

E.G. AS ABOVE, TO FIND A BASIS FOR $N(A)$, SOLVE:

$$\begin{bmatrix} a_1 & a_2 & a_3 & a_4 \\ 1 & 4 & 0 & -1 \\ 0 & 1 & 2 & 1 \\ 2 & 5 & 0 & -1 \end{bmatrix} \rightsquigarrow \begin{bmatrix} \textcircled{1} & 0 & 0 & \text{FREE} \\ 0 & \textcircled{1} & 0 & -1/3 \\ 0 & 0 & \textcircled{1} & 2/3 \end{bmatrix} \quad \begin{array}{l} a_4: \text{FREE} \\ a_1 = -1/3 a_4 \\ a_2 = 1/3 a_4 \\ a_3 = -2/3 a_4 \end{array}$$

$$\begin{bmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \end{bmatrix} = \begin{bmatrix} -1/3 a_4 \\ 1/3 a_4 \\ -2/3 a_4 \\ a_4 \end{bmatrix} = a_4 \begin{bmatrix} -1/3 \\ 1/3 \\ -2/3 \\ 1 \end{bmatrix}$$

SO $\left\{ \begin{bmatrix} -1/3 \\ 1/3 \\ -2/3 \\ 1 \end{bmatrix} \right\}$ IS A BASIS FOR $N(A)$.

6. $C(A) = \{ A\vec{x} : \vec{x} \in \mathbb{R}^n \}$ (I.E., THE IMAGE OF THE L.T. A)

- $C(A)$ IS A SUBSPACE OF \mathbb{R}^m (THE CODOMAIN OF THE L.T. A)
- WE CAN FIND A BASIS FOR $C(A)$ BY REDUCING A AND TAKING THE COLUMNS (OF OUR ORIGINAL MATRIX A!) THAT GAVE PIVOTS (JUST AS WE DO WHEN FINDING THE BASIS OF A SPAN).

E.G. AS ABOVE, A BASIS FOR $C(A)$ IS $\left\{ \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 1 \\ 5 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$.

7. (COMPUTING THE RESULT OF A MATRIX ACTING ON A COLUMN VECTOR IS JUST COMPUTING A LINEAR COMBINATION!)

$$(a) \begin{bmatrix} 2 & 1 \\ -3 & 0 \\ -1 & 5 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ -2 \end{bmatrix} = 1 \begin{bmatrix} 2 \\ -3 \\ -1 \\ 0 \end{bmatrix} - 2 \begin{bmatrix} 1 \\ 0 \\ 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ -3 \\ -11 \\ -6 \end{bmatrix}$$

$$(b) \begin{bmatrix} 3 & 0 & 1 & 4 \\ -2 & -2 & 1 & 5 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = 0 \begin{bmatrix} 3 \\ -2 \end{bmatrix} + 1 \begin{bmatrix} 0 \\ -2 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 3 \begin{bmatrix} 4 \\ 5 \end{bmatrix} = \begin{bmatrix} 14 \\ 15 \end{bmatrix}$$

$$(c) \begin{bmatrix} 4 & 1 & 3 & 0 \\ 2 & -2 & 0 & 5 \\ 1 & 0 & 4 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} = 1 \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix} - 1 \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} 3 \\ 0 \\ 4 \end{bmatrix} - 1 \begin{bmatrix} 0 \\ 5 \\ 2 \end{bmatrix} = \begin{bmatrix} 6 \\ -1 \\ 3 \end{bmatrix}$$

8. $A\vec{e}_j$ IS JUST THE j^{th} COLUMN OF A.

↳ ALL 0'S EXCEPT FOR A 1 IN THE j^{th} ENTRY

$$(b) A = \begin{bmatrix} 3 & 0 & 1 & 4 \\ -2 & -2 & 1 & 5 \end{bmatrix}; \vec{x} = \begin{bmatrix} 0 \\ 1 \\ 2 \\ 3 \end{bmatrix} = 0\vec{e}_1 + 1\vec{e}_2 + 2\vec{e}_3 + 3\vec{e}_4$$

$$A\vec{x} = A(0\vec{e}_1 + 1\vec{e}_2 + 2\vec{e}_3 + 3\vec{e}_4)$$

$$= 0 \cdot A\vec{e}_1 + 1 \cdot A\vec{e}_2 + 2 \cdot A\vec{e}_3 + 3 \cdot A\vec{e}_4 \text{ BY LINEARITY OF } A$$

$$= 0 \begin{bmatrix} 3 \\ -2 \end{bmatrix} + 1 \begin{bmatrix} 0 \\ -2 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 3 \begin{bmatrix} 4 \\ 5 \end{bmatrix} = \begin{bmatrix} 14 \\ 15 \end{bmatrix}, \text{ JUST AS IN 7(b).}$$

9. $\{A: m \times n \text{ matrix}\}$

RECALL THAT: • $N(A) = \{\vec{x} : A\vec{x} = \vec{0}\} \leftrightarrow$ L.R.'S ON THE COLUMNS OF A

• $C(A) = \{A\vec{x} : \vec{x} \in \mathbb{R}^n\} =$ SPAN OF THE COLUMNS OF A

- (a) $A\vec{x} = \vec{0}$ ONLY FOR $\vec{x} = \vec{0}$ TELLS US THAT $N(A) = \{\vec{0}\}$, SO THE ONLY L.R. ON THE COLUMNS OF A IS THE TRIVIAL ONE — I.E., THE COLUMNS OF A ARE LINEARLY INDEPENDENT.
- (b) $A\vec{x} = \vec{0}$ FOR SOME $\vec{x} \neq \vec{0}$ TELLS US THAT $N(A) \neq \{\vec{0}\}$, SO THERE IS A NONTRIVIAL L.R. ON THE COLUMNS OF A — I.E., THE COLUMNS OF A ARE LINEARLY DEPENDENT.
- (c) $A\vec{x} = \vec{b}$ HAS A SOLUTION TELLS US THAT $\vec{b} \in C(A)$ — I.E., THAT \vec{b} IS IN THE SPAN OF THE COLUMNS OF A.
- (d) $A\vec{x} = \vec{b}$ HAS NO SOLUTIONS TELLS US THAT $\vec{b} \notin C(A)$ — I.E., THAT \vec{b} IS NOT IN THE SPAN OF THE COLUMNS OF A.
- (e) FOR EACH $\vec{b} \in \mathbb{R}^m$, THE EQUATION $A\vec{x} = \vec{b}$ HAS A UNIQUE SOLUTION TELLS US THAT EVERY $\vec{b} \in \mathbb{R}^m$ CAN BE WRITTEN AS A L.C. OF THE COLUMNS OF A IN EXACTLY ONE WAY, SO THE COLUMNS OF A ARE A BASIS FOR \mathbb{R}^m . (ALTERNATIVELY, THIS TELLS US THAT WHEN A IS REDUCED, WE OBTAIN A PIVOT IN EVERY ROW + COLUMN... SO, AGAIN, THE COLUMNS OF A FORM A BASIS FOR \mathbb{R}^m).