

**Linear transformations** Suppose that  $V$  and  $W$  are vector spaces.

- $L : V \rightarrow W$  is a *linear transformation* means:

$$\forall \vec{v}_1, \dots, \vec{v}_n \in V \text{ and scalars } \alpha_1, \dots, \alpha_n, L(\alpha_1 \vec{v}_1 + \dots + \alpha_n \vec{v}_n) = \alpha_1 L\vec{v}_1 + \dots + \alpha_n L\vec{v}_n.$$

- This means that the function  $L$  and the operation of forming linear combinations commute (this can be illustrated by a *commutative diagram*).
- Three-point checklist for  $L$  to be a linear transformation:
  - $L(\vec{0}_V) = \vec{0}_W$ .
  - $\forall \vec{v} \in V$  and scalar  $\alpha$ ,  $L(\alpha \vec{v}) = \alpha L\vec{v}$ .
  - $\forall \vec{v}_1, \vec{v}_2 \in V$ ,  $L(\vec{v}_1 + \vec{v}_2) = L\vec{v}_1 + L\vec{v}_2$ .

**Kernel and image** Suppose that  $L : V \rightarrow W$  is a linear transformation.

- The *kernel* of  $L$  is  $\ker L = \{ \vec{v} \in V : L\vec{v} = \vec{0}_W \}$ , i.e.,  $\vec{v} \in \ker L \Leftrightarrow L\vec{v} = \vec{0}$ .
  - $\ker L$  is a *subspace* of the *domain* of  $L$ , relating to the *injectivity* of the function  $L$ :
    - $L\vec{v}_1 = L\vec{v}_2 \Leftrightarrow \vec{v}_1 - \vec{v}_2 \in \ker L$ .
    - $L$  is injective  $\Leftrightarrow \ker L = \{ \vec{0} \}$ .
- The *image* of  $L$  is  $\text{im } L = \{ L\vec{v} : \vec{v} \in V \}$ , i.e.,  $\vec{w} \in \text{im } L \Leftrightarrow \exists v \in V \text{ with } \vec{w} = L\vec{v}$ .
  - $\text{im } L$  is a *subspace* of the *codomain* of  $L$ , relating to the *surjectivity* of the function  $L$ :
    - $L$  is surjective  $\Leftrightarrow \text{im } L = W$ .

**Rank and nullity** Suppose that  $L : V \rightarrow W$  is a linear transformation, where  $V$  and  $W$  are finite-dimensional vector spaces.

- *Nullity*:  $\text{nullity } L \stackrel{\text{def}}{=} \dim(\ker L)$ 
  - $0 \leq \text{nullity } L \leq \dim V$ , because  $\ker L$  is a subspace of  $V$ .
  - $L$  is injective  $\Leftrightarrow \text{nullity } L = 0$ .
- *Rank*:  $\text{rank } L \stackrel{\text{def}}{=} \dim(\text{im } L)$ 
  - $0 \leq \text{rank } L \leq \dim W$ , because  $\text{im } L$  is a subspace of  $W$ .
  - $L$  is surjective  $\Leftrightarrow \text{rank } L = \dim W$ .
- The Rank+Nullity Theorem:  $\text{rank } L + \text{nullity } L = \dim V$ .
  - Outline of proof: take a basis for  $\ker L$ , and extend it to a basis for  $V$ ; apply  $L$  to the non-kernel basis vectors above and show that these form a basis for  $\text{im } L$ , then count the vectors in the bases to determine dimensions.

**Linear transformations from collections and from matrices**

- A collection  $\mathcal{C} = (\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n)$  of vectors in  $V$  defines a linear transformation  $[\mathcal{C}] : \mathbb{R}^n \rightarrow V$ ,

defined by forming linear combinations: 
$$[\mathcal{C}] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \stackrel{\text{def}}{=} x_1 \vec{v}_1 + \dots + x_n \vec{v}_n.$$

- $\ker [\mathcal{C}] \Leftrightarrow$  (coefficients for) linear relations on  $\mathcal{C}$  (so  $[\mathcal{C}]$  is injective  $\Leftrightarrow \mathcal{C}$  is linearly independent in  $V$ ).
- $\text{im } [\mathcal{C}] = \text{span } \mathcal{C}$  (so  $[\mathcal{C}]$  is surjective  $\Leftrightarrow \mathcal{C}$  spans  $V$ ). (Thus,  $[\mathcal{C}]$  is bijective  $\Leftrightarrow \mathcal{C}$  is a basis for  $V$ .)

- An  $m \times n$  matrix  $A$  gives a linear transformation  $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$  defined by forming linear combinations of its *columns*:

$$A \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \stackrel{\text{def}}{=} x_1 [1^{\text{st}} \text{ col. of } A] + \dots + x_n [n^{\text{th}} \text{ col. of } A].$$

- $\ker A$  is the set of solutions to the homogeneous system  $[A | \vec{0}]$  (also known as  $N(A)$ , the *nullspace* of  $A$ ).
  - We can find a *basis* for  $N(A)$  simply by finding the free variables' contributions to the solution of the homogeneous system  $[A | \vec{0}]$ .
- $\text{im } A$  is the span of the columns of  $A$  (also known as  $C(A)$ , the *column space* of  $A$ ).
  - We can find a *basis* for  $C(A)$  simply by reducing  $A$  and taking the columns of  $A$  that gave pivots.
- Matrices and the standard basis:  $A\vec{e}_j = j^{\text{th}} \text{ column of } A$ .