

Inner product spaces Let V be a real vector space.

- An *inner product* on V is a symmetric, positive-definite [bilinear] 2-form on V , i.e., a function that maps each pair of vectors $\vec{v}, \vec{w} \in V$ to their inner product $\langle \vec{v}, \vec{w} \rangle \in \mathbb{R}$, with the following properties:

- Bilinear:** $\langle \alpha \vec{v}, \vec{w} \rangle = \alpha \langle \vec{v}, \vec{w} \rangle = \langle \vec{v}, \alpha \vec{w} \rangle$ ($\forall \vec{v}, \vec{w} \in V$ and $\alpha \in \mathbb{R}$)
 $\langle \vec{v}_1 + \vec{v}_2, \vec{w} \rangle = \langle \vec{v}_1, \vec{w} \rangle + \langle \vec{v}_2, \vec{w} \rangle$ ($\forall \vec{v}_1, \vec{v}_2, \vec{w} \in V$)
 $\langle \vec{v}, \vec{w}_1 + \vec{w}_2 \rangle = \langle \vec{v}, \vec{w}_1 \rangle + \langle \vec{v}, \vec{w}_2 \rangle$ ($\forall \vec{v}, \vec{w}_1, \vec{w}_2 \in V$)
- Symmetric:** $\forall \vec{v}, \vec{w} \in V, \langle \vec{v}, \vec{w} \rangle = \langle \vec{w}, \vec{v} \rangle$
- Positive-definite:** $\langle \vec{v}, \vec{v} \rangle \geq 0$ ($\forall \vec{v} \in V$)
 $\langle \vec{v}, \vec{v} \rangle = 0 \Rightarrow \vec{v} = \vec{0}$

- $\langle \vec{v}, \vec{w} \rangle$ can be intuitively interpreted as the degree of “agreement” of the vectors \vec{v} and \vec{w} .

- Given an inner product $\langle \cdot, \cdot \rangle$ on V , we define the *norm* of a vector $\vec{v} \in V$ by $\|\vec{v}\| \stackrel{\text{def}}{=} \sqrt{\langle \vec{v}, \vec{v} \rangle}$.

This norm has the following properties:

- Absolutely homogeneous:** $\|\alpha \vec{v}\| = |\alpha| \|\vec{v}\|$ ($\forall \vec{v} \in V$ and $\alpha \in \mathbb{R}$)
- Positive-definite:** $\|\vec{v}\| \geq 0$ ($\forall \vec{v} \in V$)
 $\|\vec{v}\| = 0 \Rightarrow \vec{v} = \vec{0}$

- $\|\vec{v}\|$ is geometrically interpreted as the “length” of \vec{v} , with $\|\vec{v} - \vec{w}\|$ representing the *distance* between \vec{v} and \vec{w} .

- An *inner product space* is a real vector space V equipped with an inner product $\langle \cdot, \cdot \rangle$.

- In an inner product space, we have not only the linear algebra concepts arising from linear combinations, but also notions such as distance, length, angles, projection, and approximation.

- Two common inner product spaces:

- \mathbb{R}^m , equipped with the *dot product* $\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{bmatrix} \cdot \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix} \stackrel{\text{def}}{=} x_1 y_1 + x_2 y_2 + \dots + x_m y_m$

and the resulting norm $\left\| \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{bmatrix} \right\| = \sqrt{x_1^2 + x_2^2 + \dots + x_m^2}$.

- $C([a, b])$, equipped with the inner product $\langle f, g \rangle \stackrel{\text{def}}{=} \int_a^b f g$ (or some scaling thereof)

and the resulting norm $\|f\| = \sqrt{\int_a^b f^2}$.

- Two important inequalities hold in *any* inner product space:

- The Cauchy-Schwarz Inequality: $|\langle \vec{v}, \vec{w} \rangle| \leq \|\vec{v}\| \|\vec{w}\|$.
- The Triangle Inequality: $\|\vec{v} + \vec{w}\| \leq \|\vec{v}\| + \|\vec{w}\|$, and its counterpart, $\|\vec{v} + \vec{w}\| \geq |\|\vec{v}\| - \|\vec{w}\||$.

The transpose In \mathbb{R}^m , we can *transpose* matrices and vectors by turning their columns into rows.

- The transpose is linear: $(\alpha A)^T = \alpha(A^T)$ and $(A + B)^T = A^T + B^T$.
- The transpose *reverses* the order of compositions: $(AB)^T = B^T A^T$.

...and the dot product

Suppose that: $\vec{x}, \vec{y} \in \mathbb{R}^m$. $A = \left[\begin{array}{c|c|c} \vec{a}_1 & \dots & \vec{a}_n \end{array} \right]$ is an $m \times n$ matrix. $B = \left[\begin{array}{c|c|c} \vec{b}_1 & \dots & \vec{b}_p \end{array} \right]$ is an $m \times p$ matrix.

The transpose relates to the dot product in the following ways:

<u>Vector-Vector</u>	<u>Matrix-Vector</u>	<u>Matrix-Matrix</u>
$\vec{x}^T \vec{y} = \vec{x} \cdot \vec{y}$	$A^T \vec{x} = \begin{bmatrix} \vec{a}_1 \cdot \vec{x} \\ \vdots \\ \vec{a}_n \cdot \vec{x} \end{bmatrix}$	$A^T B = \begin{bmatrix} \vec{a}_1 \cdot \vec{b}_1 & \dots & \vec{a}_1 \cdot \vec{b}_p \\ \vdots & \dots & \vdots \\ \vec{a}_n \cdot \vec{b}_1 & \dots & \vec{a}_n \cdot \vec{b}_p \end{bmatrix}$

Orthogonality and vector projection Suppose that V is an inner product space.

- Orthogonality:
 - vector-vector: if $\vec{v}, \vec{w} \in V$, then $\vec{v} \perp \vec{w}$ means $\langle \vec{v}, \vec{w} \rangle = 0$, read “ \vec{v} and \vec{w} are *orthogonal*”.
 - vector-subspace: if $\vec{v} \in V$ and W is a subspace of V , then $\vec{v} \perp W$ means $\forall \vec{w} \in W, \vec{v} \perp \vec{w}$.
 - subspace-subspace: if W, W' are subspaces of V , then $W \perp W'$ means $\forall \vec{w} \in W \text{ and } \vec{w}' \in W', \vec{w} \perp \vec{w}'$.
- $\vec{v} \in V$ is a *unit vector* means $\|\vec{v}\| = 1$, i.e., $\langle \vec{v}, \vec{v} \rangle = 1$.
 - Any nonzero vector $\vec{v} \in V$ can be *normalized*, i.e., converted into a unit vector in the same direction, via $\vec{v} \rightsquigarrow \frac{1}{\|\vec{v}\|} \vec{v}$.
- The Pythagorean Theorem holds for orthogonal vectors in any inner product space: $\vec{v} \perp \vec{w} \Leftrightarrow \|\vec{v} + \vec{w}\|^2 = \|\vec{v}\|^2 + \|\vec{w}\|^2$.
 - Important consequence: if $\vec{n} \perp W$, then $\forall \vec{w} \in W, \|\vec{n} + \vec{w}\| \geq \|\vec{n}\|$.
- The *vector projection* of $\vec{v} \in V$ onto a nonzero vector $\vec{w} \in V$ is defined by $\text{proj}_{\vec{w}} \vec{v} = \frac{\langle \vec{v}, \vec{w} \rangle}{\langle \vec{w}, \vec{w} \rangle} \vec{w}$.
 - $\text{proj}_{\vec{w}} \vec{v}$ is the multiple of \vec{w} that best approximates \vec{v} .
 - Proven by minimizing the function $f(\alpha) = \|\vec{v} - \alpha \vec{w}\|^2$.
 - Defining $\text{orth}_{\vec{w}} \vec{v} = \vec{v} - \text{proj}_{\vec{w}} \vec{v}$, we find that $\text{orth}_{\vec{w}} \vec{v} \perp \vec{w}$; thus, $\vec{v} = \text{proj}_{\vec{w}} \vec{v} + \text{orth}_{\vec{w}} \vec{v}$ expresses any vector \vec{v} as a multiple of \vec{w} plus a vector orthogonal to \vec{w} .
 - In the case that \vec{w} is a unit vector, the projection formula $\text{proj}_{\vec{w}} \vec{v}$ simplifies to $\langle \vec{v}, \vec{w} \rangle \vec{w}$.

Orthonormal collections

A collection $\mathcal{U} = \{ \vec{u}_1, \vec{u}_2, \dots, \vec{u}_k \}$ is *orthonormal* means that $\forall i, j, \langle \vec{u}_i, \vec{u}_j \rangle = \delta_{ij} \stackrel{\text{def}}{=} \begin{cases} 1, & \text{if } i = j \\ 0, & \text{if } i \neq j \end{cases}$;

in other words, \mathcal{U} is orthonormal if the vectors of \mathcal{U} are mutually orthogonal unit vectors.

- If \mathcal{C} is an orthonormal collection, then \mathcal{C} is linearly independent.
- Any finite collection \mathcal{C} in V can be converted into an *orthonormal* collection $\mathcal{U} = \{ \vec{u}_1, \vec{u}_2, \dots, \vec{u}_k \}$ having the same span (i.e., an orthonormal basis for $\text{span } \mathcal{C}$) by the *Gram-Schmidt Process*:
For each vector \vec{v} of \mathcal{C} in turn:
 - Subtract its projections onto the vectors of \mathcal{U} so far obtained: $\vec{v} \rightsquigarrow \vec{v}' = \vec{v} - \langle \vec{v}, \vec{u}_1 \rangle \vec{u}_1 - \langle \vec{v}, \vec{u}_2 \rangle \vec{u}_2 - \dots$
 - If $\vec{v}' = \vec{0}$, toss it out; otherwise, normalize it and append it to the orthonormal collection: $\frac{1}{\|\vec{v}'\|} \vec{v}' \rightsquigarrow \mathcal{U}$.

Tip: Keep any messy scalars resulting from normalization outside the vectors, rather than distributing them to the entries.
- Some useful orthonormal collections:
 - The standard basis $(\vec{e}_1, \vec{e}_2, \dots, \vec{e}_n)$ for \mathbb{R}^n is orthonormal (with respect to the dot product).
 - The collection $\{ \frac{1}{\sqrt{2}}, \cos x, \sin x, \cos 2x, \sin 2x, \dots \}$ is orthonormal in $C([- \pi, \pi])$ (with respect to the inner product $\langle f, g \rangle = \frac{1}{\pi} \int_{-\pi}^{\pi} fg$).

Projection and orthonormal collections

Suppose that $W = \text{span} \{ \vec{w}_1, \vec{w}_2, \dots, \vec{w}_n \}$ is the subspace spanned by an *orthonormal* collection in an inner product space V .

- The *orthogonal projection* of $\vec{v} \in V$ onto W is given by $\text{proj}_W \vec{v} = \langle \vec{v}, \vec{w}_1 \rangle \vec{w}_1 + \langle \vec{v}, \vec{w}_2 \rangle \vec{w}_2 + \dots + \langle \vec{v}, \vec{w}_n \rangle \vec{w}_n$.
 - Defining $\text{orth}_W \vec{v} = \vec{v} - \text{proj}_W \vec{v}$, we find that $\text{orth}_W \vec{v} \perp W$;
thus, $\vec{v} = \text{proj}_W \vec{v} + \text{orth}_W \vec{v}$ expresses any vector \vec{v} as a vector of W plus a vector orthogonal to W .
 - $\text{proj}_W \vec{v}$ is the vector of W that best approximates \vec{v} .
 - Proven via the corollary to the Pythagorean Theorem and the fact that $\text{orth}_W \vec{v} \perp W$.
- Example: Fourier polynomials for continuous functions on $[-\pi, \pi]$.
 - The collection $\mathcal{F}_n = \{ \frac{1}{\sqrt{2}}, \cos x, \sin x, \cos 2x, \sin 2x, \dots, \cos nx, \sin nx \}$ is orthonormal in $C([-\pi, \pi])$ (with respect to the inner product $\langle f, g \rangle = \frac{1}{\pi} \int_{-\pi}^{\pi} fg$).
 - Given $f(x) \in C([-\pi, \pi])$, the n^{th} -order Fourier polynomial for $f(x)$ is:

$$\text{proj}_{\text{span } \mathcal{F}_n} f(x) = \left\langle f(x), \frac{1}{\sqrt{2}} \right\rangle \frac{1}{\sqrt{2}} + \langle f(x), \cos x \rangle \cos x + \langle f(x), \sin x \rangle \sin x + \dots + \langle f(x), \cos nx \rangle \cos nx + \langle f(x), \sin nx \rangle \sin nx$$

This function is the linear combination of such sines and cosines that best approximates $f(x)$ on $[-\pi, \pi]$.

Projection matrices and approximation for linear systems

Suppose that A is an $m \times n$ matrix with linearly independent columns.

- $A^T A$ is invertible, so we can define the *projection matrix* $P = A(A^T A)^{-1} A^T : \mathbb{R}^m \rightarrow \mathbb{R}^m$.
 - P maps vectors orthogonal to $C(A)$ to zero: $\forall \vec{y} \perp C(A), P\vec{y} = \vec{0}$.
 - P maps vectors in $C(A)$ to themselves: $\forall \vec{y} \in C(A), P\vec{y} = \vec{y}$.
 - Applying these results to any vector $\vec{v} = \text{proj}_{C(A)} \vec{v} + \text{orth}_{C(A)} \vec{v}$ shows us that $P\vec{v} = \text{proj}_{C(A)} \vec{v}$.
 - Thus, given *any* basis for a subspace of \mathbb{R}^m (not necessarily orthonormal), P allows us to project any vector of \mathbb{R}^m onto their span (by placing the basis vectors into the matrix A and computing P).
- This allows us find the best approximate solution to an *inconsistent* system $[A \mid \vec{b}]$, as follows:
 - Even if the linear system $A\vec{x} = \vec{b}$ is inconsistent, the system $A\vec{x} = P\vec{b}$ is consistent because $P\vec{b} \in C(A)$.
 - From this, we can find the best approximate solution to our original system by transforming it as follows:

$$[A \mid \vec{b}] \rightsquigarrow [A^T A \mid A^T \vec{b}]$$

consistent!

- Application: Curve-Fitting
We can find the best-fitting curve (line, polynomial, exponential, etc.) to some given set of data, simply by using the data points to set up a [possibly inconsistent] system for the coefficients involved, then using the above method to find the best approximate solution.